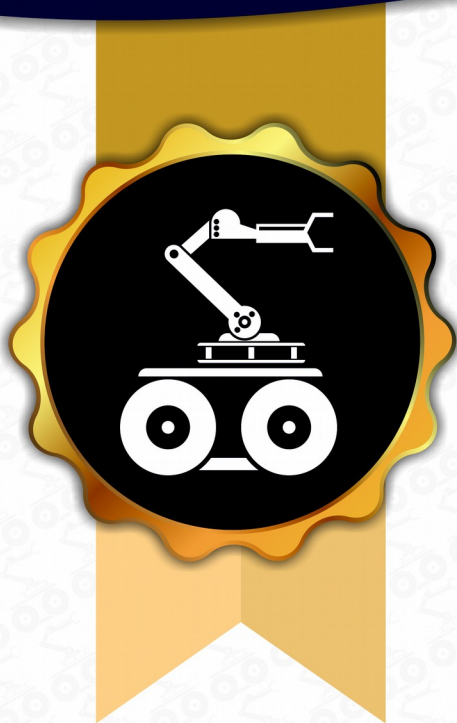


18th IEEE Latin American Robotics Symposium - LARS 2021

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Article Presentation Certificate



This is to certify that the paper 217725 titled "Tracking Nonlinear Model Predictive Control for Obstacle Avoidance" authored by Marcelo Santos, Antonio Ferramosca, Guilherme Raffo has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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