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Article Presentation Certificate



This is to certify that the paper 217874 titled “A New Approach of Monocular Visual Odometry to Trajectory Estimation Within a Plantation” authored by Gabriel Araujo, Jorge Id Filho, Vitor Higuti, Marcelo Becker has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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