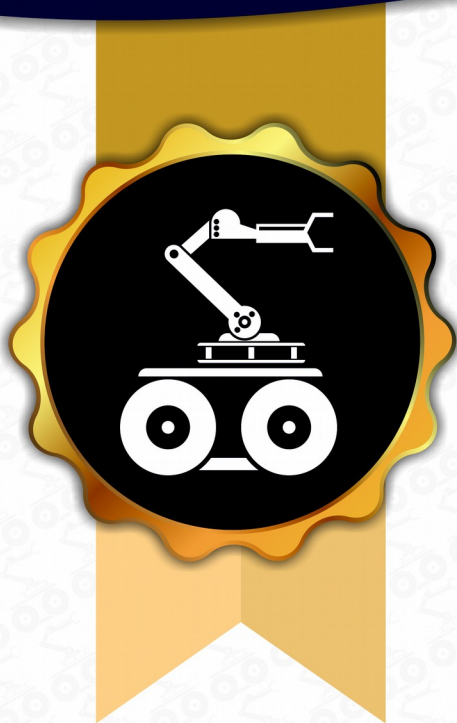


18th IEEE Latin American Robotics Symposium - LARS 2021

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Article Presentation Certificate



This is to certify that the paper 218114 titled “6D Robotic Grasping System using Convolutional Neural Networks and Adaptive Artificial Potential Fields with Orientation Control” authored by Caio Viturino, Daniel Oliveira, Andre Gustavo Scolari Conceicao, Ubiratan Junior has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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