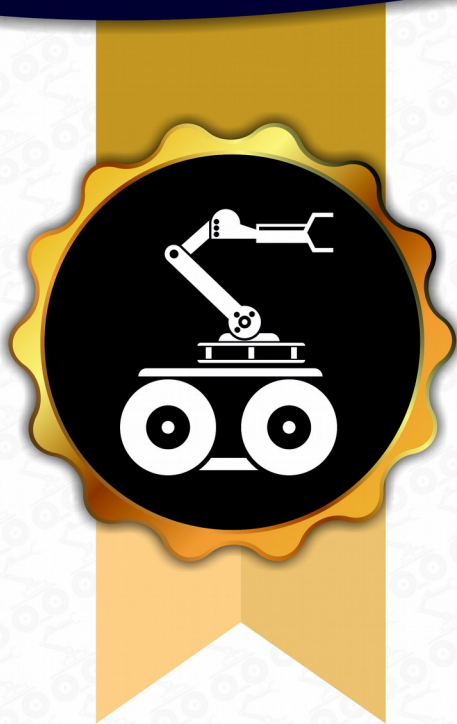# 18th IEEE Latin American Robotics Symposium - LARS 2021

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Article Presentation Certificate

This is to certify that the paper 218796 titled "Comparison of Visual SLAM Algorithms ORB-SLAM2, RTAB-Map and SPTAM in an Internal and External Environments with ROS" authored by Kesse Jonatas De Jesus, Henry Kobs, Marco Cuadros, Daniel Fernando T. Gamarra, Anselmo Rafael Cukla has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

Prof. Dr. Luiz Marcos Garcia Gonçalves - UFRN

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