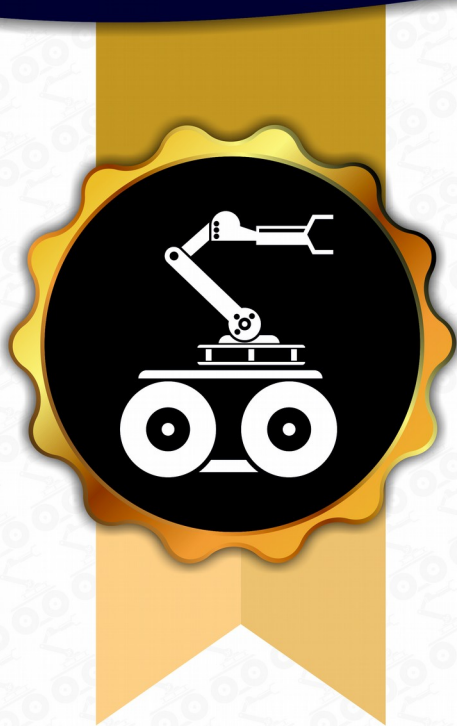


18th IEEE Latin American Robotics Symposium - LARS 2021

13th Brazilian Symposium of Robotics - SBR 2021

Article Presentation Certificate



This is to certify that the paper 219007 titled “Localization Using OpenStreetMap Landmarks” authored by Maximilian Kunz, Axel Vierling, Patrick Wolf, Karsten Berns has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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