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This is to certify that the paper 219053 titled "A Framework to Improve SLAM Algorithms for Crowded Human Environments" authored by Kevin Inofuente, Sergio Junior, Dennis Barrios-Araníbar, Yudith Cardinale, Jose A. Diaz-Amado has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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