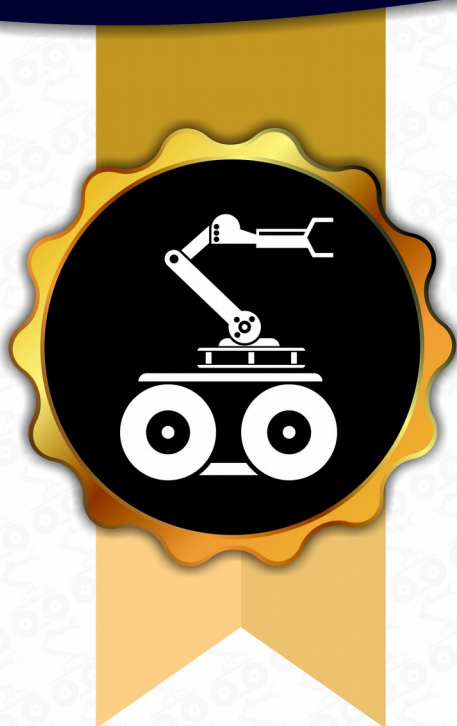


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Article Presentation Certificate



This is to certify that the paper 219209 titled “Dynamic Modeling and Control Optimization of Free-Floating Dual-Arm Space Robots in Task Space” authored by Tatiana Pazelli, Gabriel Rodrigues has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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