

18th IEEE Latin American Robotics Symposium - LARS 2021

13th Brazilian Symposium of Robotics - SBR 2021

Certificate for Best Papers



This is to certify that the paper titled "Tracking Nonlinear Model Predictive Control for Obstacle Avoidance" authored by Marcelo Santos (UFMG), Antonio Ferramosca (University of Bergamo), Guilherme Raffo (UFMG) that has been presented at joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) held in Natal, RN, Brazil, from 11th to 15th of October, 2021, has been awarded the third place between the best papers of LARS-SBR 2021 .

Prof. Dr. Luiz Marcos Garcia Gonçalves - UFRN

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