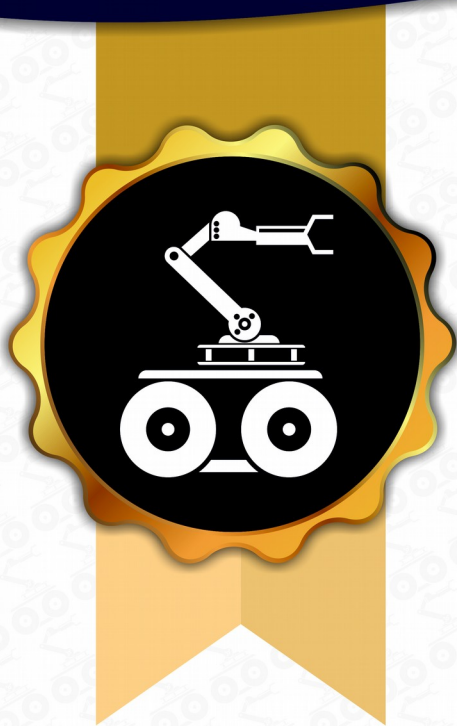# 18th IEEE Latin American Robotics Symposium - LARS 2021

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Article Presentation Certificate

This is to certify that the paper 217633 titled "INTERFACE DE CONTROLE POR MÉTODOS DE AUTONOMIA ADAPTÁVEL DESLIZANTE PARA ROBÔS DE INSPEÇÃO" authored by Piatan Palar (UTFPR) and Andre Schneider de Oliveira (UTFPR) has been presented in category Master of track Thesis and Dissertation Contest at the joint event Latin American Robotics Symposium (LARS), Brazilian Robotics Symposium (SBR), and Workshop of Robotics in Education (WRE) that was held in Natal, RN, Brazil, from 11th to 15th of October, 2021.

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